

SYLLABUS

1. Data about the program of study

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| 1.1 | Institution | Technical University of Cluj-Napoca |
| 1.2 | Faculty | Faculty of Electrical Engineering |
| 1.3 | Department | Electrotechnics and Measurements |
| 1.4 | Field of study | Electrical Engineering |
| 1.5 | Cycle of study | Bachelor of Science |
| 1.6 | Program of study/Qualification | Electrical System Cluj-Napoca in English language |
| 1.7 | Form of education | Full time |
| 1.8 | Subject code | 42.00 |

2. Data about the subject

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|----------------|--------------------------------|--|--------------|----|
| 2.1 | Subject name | Electrical Drives | | |
| 2.2 | Course responsible/lecturer | Prof. Eng. Iulian Birou, Phd (birou@edr.utcluj.ro), | | |
| 2.3 | Teachers in charge of seminars | Lecturer eng. Szabo Csaba, Phd (Csaba.Szabo@emd.utcluj.ro) Asist. Eng. Mihai Suciu, Phd (Mihai.Suciu@emd.utcluj.ro) | | |
| 2.4 | Year of study | III | 2.5 Semester | 2 |
| 2.6 Assessment | | | | Ex |
| 2.7 | Subject category | Formative category | | DD |
| | | Optionality | | DI |

3. Estimated total time

| | | | | | | | | | | | |
|--|-------------------------------|----|----------|------------|-----|-------------|--|----------------|----|-------------|----|
| 3.1 | Number of hours per week | 5 | of which | 3.2 Course | 2 | 3.3 Seminar | | 3.3 Laboratory | 2 | 3.3 Project | 1 |
| 3.4 | Total hours in the curriculum | 70 | of which | 3.5 Course | 28 | 3.6 Seminar | | 3.6 Laboratory | 28 | 3.6 Project | 14 |
| 3.7 Individual study: 44 | | | | | | | | | | | |
| (a) Manual, lecture material and notes, bibliography | | | | | | | | | | 16 | |
| (b) Supplementary study in the library, online and in the field | | | | | | | | | | 8 | |
| (c) Preparation for seminars/laboratory works, homework, reports, portfolios, essays | | | | | | | | | | 26 | |
| (d) Tutoring | | | | | | | | | | 2 | |
| (e) Exams and tests | | | | | | | | | | 3 | |
| (f) Other activities | | | | | | | | | | | |
| 3.8 Total hours of individual study (summ (3.7(a)...3.7(f))) | | | | | 55 | | | | | | |
| 3.9 Total hours per semester (3.4+3.8) | | | | | 125 | | | | | | |
| 3.10 Number of credit points | | | | | 5 | | | | | | |

4. Pre-requisites (where appropriate)

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| 4.1 | Curriculum | General knowledge on System Theory, Electrotechnics, Electrical Machines, Power Electronics |
| 4.2 | Competence | Specific competences related to System Theory, Electrical Machines, Power Electronics |

5. Requirements (where appropriate)

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| 5.1 | For the course | |
| 5.2 | For the applications Seminar /Laboratory/Project | Mandatory presence |

6. Specific competences

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| Professional competences | <p>C6. Design and control of electrical drive systems</p> <p>C6.1. Identification of fundamental aspects specific related to system theory and automated control, and of the investigation methods of an electrical drive system.</p> <p>C6.3. Application of control principles and specific procedures used for optimization of working parameters of a control system, for evaluation of the working limits of an electrical drive system.</p> <p>C6.4. Development of digital control based electrical drives fed by power electronic converters controlled by dedicated microprocessor or DSP based systems.</p> <p>C6.5. Development of a control system of reduced complexity of an industrial process using specific techniques and procedures.</p> |
| Cross competences | <p>CT1 Identification of the main objectives, available resources, completion conditions, work steps, work times, terms and related risks.</p> <p>CT3 Efficient use of documentation and communication resources and assisted professional training (on-line database, specific software and hardware solutions).</p> |

7. Expected learning outcomes

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| Knowledge | The student/graduate analyzes well-defined electrical engineering problems; identifies relevant standards and regulations, and uses appropriate engineering resources and tools. |
| Abilities | <p>The student/graduate creates drawings of electrical panels, electrical schematics, wiring diagrams, and other assembly details.</p> <p>The student/graduate selects and applies current methods of modeling, calculation, design, and testing specific to their field of specialization.</p> |
| Responsibility and autonomy | The student/graduate reflects critically and responsibly, in a democratic spirit, on the ethical and social responsibilities associated with managing activities in electrical engineering, decision-making, and forming professional opinions. |

8. Discipline objectives (as results from the *key competences gained*)

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| 8.1 | General objective | To know the electrical drive systems with DC and AC machine fed by power converters. To know the scalar control, vector control and direct torque control of induction and synchronous machines, both in motor and generator regime. |
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| 8.2 | Specific objectives | <p>After the completion of this course, students will be able:</p> <ul style="list-style-type: none"> - To chose and to control an electrical drive system for a specific application; - To integrate the electrical drive system in a motion control process or in a power generating process. - To identify, to design and to assembly the components of an adjustable speed electrical driving system (electrical machine, power converter, mechanical process, control system, digital computer); - To measure the parameters of an electrical drive system |
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9. Contents

| 9.1. Lecture (syllabus) | Number of hours | Teaching methods | Notes |
|---|-----------------|---|-------|
| The structure of a performant electrical drive system. Power flow components and information Flow components. | 2 | Multimedia presentation, group projects, case studies | |
| Basic principals of electrical drives. Mechanical elements and power efficiency of electrical drives, stability criteria and applications of electrical drives | 2 | | |
| Electrical drive systems with DC machines fed by rectifiers and choppers; control functions | 4 | | |
| Control diagram of DC drive system | 2 | | |
| Basic principals of three-phase AC electrical machines (IM and SM); rotating field, equations, characteristics | 2 | | |
| Scalar control ($U/f=ct$) of AC drives | 2 | | |
| Vector control of AC drives. Principals, equivalence with DC drive control, power converters for AC drives, control strategies. | 8 | | |
| Direct torque control of AC drives | 2 | | |
| Electrical drive systems with AC machines used for producing electrical energy. Constant speed generating systems and variable speed generating systems (renewable energy generating systems) | 2 | | |
| Transducers and digital computing systems used for performant electrical drive systems. Modern control strategies | 2 | | |
| Bibliography 1. Kelemen, A.: <i>Acționări electrice</i> . Ed. Didactică și Pedagogică, București, 1979. 2. Iulian Birou - <i>Metode performante de control in actionari electrice de curent alternativ</i> . Editura Casa cartii de stiinta, 1999. 3. Kelemen, A., Imecs, M.: <i>Sisteme de reglare cu orientare după câmp ale mașinilor de curent alternativ</i> . Lito I.P.C.N. 1987 sau Editura Academiei Române, București, 1989. 4. Iulian Birou – <i>Actionari electrice; Sisteme de reglare si control</i> . Editura Mediamira, 2003 5. Kelemen, A., Imecs, M.: <i>Electronică de putere</i> . Ed. Didactică și Pedagogică, București, 1983. | | | |
| 9.2. Laboratory | Number of hours | Teaching methods | Notes |
| 1.a. DC drive system with PM excitation, fed by power converter 1.b. Drive system with DC machine fed in both in rotor and stator by power converters | 4 | | |
| 2a. Drive system with DC machines for elevators (2 quadrant) 2b. Drive system with DC machines for 4 quadrant applications | 4 | | |
| 3a Control of a DC drive system fed by 4 quadrant rectifier 3b. Control of a DC drive system fed by 4 quadrant chopper | 4 | | |
| 4a. Electrical drive system with three-phase rotor winding induction machine. | 4 | | |

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| 4b. Scalar control of three-phase squirrel-cage induction machine (DSP based open loop $U/f=ct.$) | | | |
| 5a. AC drive system with induction machine fed by a current converter 5b. Scalar control of three-phase induction machine (DSP based close-loop control $U/f=ct.$ With initial boost voltage). | 4 | | |
| 6a. Vector control of an induction machine based on rotor field orientation fed by PWM voltage converter. 6b. Vector control of a permanent-magnet synchronous fed by PWM voltage converter. | 4 | | |
| Final presentation and evaluation | 4 | | |
| Bibliography <i>A acționări electrice - Îndrumător pentru lucrări de laborator</i> , versiune electronica, 2019 | | | |
| 9.2 Project | Number of hours | Teaching methods | Notes |
| Specific project to design and compute an electrical drive application with DC or AC machine. | 14 | | |
| Bibliography <i>A acționări electrice - Îndrumător pentru proiectare</i> , versiune electronica, 2014. | | | |

10. Bridging course contents with the expectations of the representatives of the community, professional associations and employers in the field

11. Evaluation

| Activity type | 11.1 Assessment criteria | 11.2 Assessment methods | 11.3 Weight in the final grade |
|---|---|-------------------------------------|--------------------------------|
| 11.4 Course | Evaluation of the acquired knowledge during the course activities: theoretical and application-based exam | Written and oral exam (3h) | 55% |
| 11.5 Seminar/ Laboratory/Project | Evaluation of the acquired competences based on: - Activity during lab - theoretical and practical tests - portfolio | - portfolio presentation - tests | 45% |
| 11.6 Minimum standard of performance | | | |
| Completion and presentation of laboratory activities, laboratory portfolio presentation. Final examination. Minimum final grade for lab and project: 5. Minimum final grade for exam: 4.5 | | | |

| Date of completion | Lecturers | Title/ Surname/ Name: | Signature |
|---------------------------|---|--------------------------------|------------------|
| January 2026 | Course | Prof. Eng. Iulian Birou, Phd | |
| | Applications Seminar/ Laboratory/ Project | Lecturer eng. Szabo Csaba, Phd | |
| | | Asist. Eng. Mihai Suciu, Phd) | |

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| Date of approval in the ETHM Department Council January 2026 | Head of Department: Prof. Eng. MICU Dan Doru, PhD |
| Date of approval in the Faculty of Electrical Engineering Council February 2026 | Dean: Assoc. Prof. Eng. CZIKER Andrei, PhD |